Most of our work will make use of the matrix mechanics formulation of quantum mechanics. The wavefunction is written as \(|\Psi\rangle\) and referred to as a *ket* vector. The complex conjugate \(\langle\Psi|\) is a *bra* vector, where \(\langle\Psi| = a^* \langle\Psi|\). The product of a bra and ket vector, \(\langle\Psi|\alpha\rangle \langle\beta|\) is therefore an *inner product* (scalar or dot product), whereas the product of a ket and bra \(|\beta\rangle\langle\alpha|\) is an *outer product* (matrix). The use of bra–ket vectors is the *Dirac notation* in quantum mechanics.

In the matrix representation, \(|\Psi\rangle\) is represented as a column vector for the expansion coefficients \(c_i\) in a particular basis set.

\[
|\Psi\rangle = \begin{pmatrix} c_1 \\ c_2 \\ c_3 \\ \vdots \end{pmatrix}
\]

The bra vector \(\langle\Psi|\) refers to a row vector of the conjugate expansion coefficients \(c_i^*\). Since wavefunctions are *normalized*, \(\langle\Psi|\Psi\rangle = 1\). Dirac notation has the advantage of brevity, often shortening the wavefunction to a simple abbreviated notation for the relevant quantum numbers in the problem. For instance, we can write Equation \ref{14} as

\[
|\Psi\rangle = \sum_i c_i |i\rangle
\]

where the sum is over all eigenstates and the \(i^{th}\) eigenstate \(|i\rangle\). Implicit in this equation is that the expansion coefficient for the \(i^{th}\) eigenstate is

\[
c_i = \langle i|\Psi\rangle.
\]

With this brevity comes the tendency to hide some of the variables important to the description of the wavefunction. One has to be aware of this, and although we will use *Dirac notation* for most of our work, where detail is required, Schrödinger notation will be used.

The outer product \(|i\rangle\langle i|\) is known as a *projection operator* because it can be used to project the wavefunction of the system onto the \(|i\rangle\) eigenstate of the system as

\[
|i\rangle\langle i|\Psi\rangle = c_i |i\rangle
\]

Furthermore, if we sum projection operators over the complete basis set, we obtain an identity operator

\[
\sum_i |i\rangle\langle i| = 1
\]

which is a statement of the completeness of a basis set. The orthogonality of eigenfunctions (Equation \ref{8}) is summarized as \(\langle i|j\rangle = \delta_{ij}\). The operator \(|\hat{A}\rangle\rangle\) is a square matrix that maps from one state to another

\[
|\hat{A}\rangle\rangle |\Psi\rangle = |\Psi\rangle
\]

and from Equation \ref{6} the TISE is

\[
|\hat{H}\rangle\rangle |\Psi\rangle = E |\Psi\rangle
\]
where \( E \) is a diagonal matrix of eigenvalues whose solution is obtained from the characteristic equation

\[
\operatorname{det}(H - E \mathbf{I}) = 0 \label{19}
\]

The expectation value, a restatement of Equation \ref{10}, is written

\[
\langle A \rangle = \langle \Psi | \hat{A} | \Psi \rangle \label{20}
\]

or from Equation \ref{15}

\[
\langle A \rangle = \sum_i \sum_j c_i^* c_j A_{jj} \label{21}
\]

where \( A_{ij} = \langle i | A | j \rangle \) are the matrix elements of the operator \( \hat{A} \). As we will see later, the matrix of expansion coefficients \( \rho_{ij} = c_i^* c_j \) is known as the density matrix. From Equation \ref{18}, we see that the expectation value of the Hamiltonian is the energy of the system,

\[
E = \langle \Psi | H | \Psi \rangle \label{22}
\]

Hermitian operators play a special role in quantum mechanics. The Hermitian adjoint of an operator \( \hat{A} \) is written \( \hat{A}^\dagger \), and is defined as the conjugate transpose of \( \hat{A} \):

\[
\langle \hat{A} | \phi \rangle = \langle \psi | \hat{A}^\dagger \phi \rangle \]

A Hermitian operator is one that is self-adjoint, i.e.,

\[
\hat{A}^\dagger = A.\]

For a Hermitian operator, a unique unitary transformation exists that will diagonalize it.

Each basis set provides a different route to representing the same physical system, and a similarity transformation \( S \) transforms a matrix from one orthonormal basis to another. A transformation from the state \( | \Psi \rangle \) to the state \( | \Phi \rangle \) can be expressed as

\[
| \Theta \rangle = S | \Psi \rangle \label{23}
\]

where the elements of the matrix are \( S_{ij} = \langle \theta_i | \psi_j \rangle \). Then the reverse transformation is

\[
| \Psi \rangle = S^\dagger | \Theta \rangle \label{24}
\]

Therefore \( S^\dagger S = 1 \) and the transformation is said to be unitary. A unitary transformation refers to a similarity transformation in Hilbert space that preserves the scalar product, i.e., the length of the vector. The transformation of an operator from one basis to another is obtained from \( S^\dagger (\hat{A}) S \), and diagonalizing refers to finding the unitary transformation that puts the matrix \( \hat{A} \) in diagonal form.